

# 3D Graphics in Sage

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12 August 2008

# Brief History

3D Graphics in Sage was a long time in coming

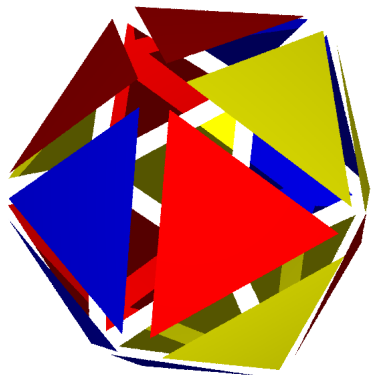
- summer 2006 — tachyon, notebook
- spring 2007 — first attempt (xj3d)
- summer 2007 — second attempt (java3d)
- December 2007 — discover jmol
- August 2008 — Sage Days 9

# Status

- Now we have a stable, working core to build on
- Jmol used from command line and notebook
- still lots of unimplemented features

William Stein's talk will be about the front end, I will focus on the underlying implementation.

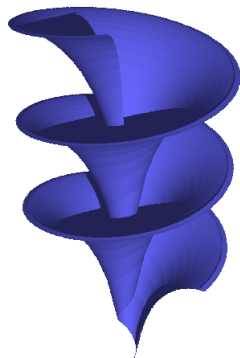
# IndexFaceSet



- bread and butter 3D graphics
- represent triangulated graphics
  - suboptimal for jmol, tachyon
- list of vertices
- list of faces by *indexing* into vertex list

# ParametricSurface

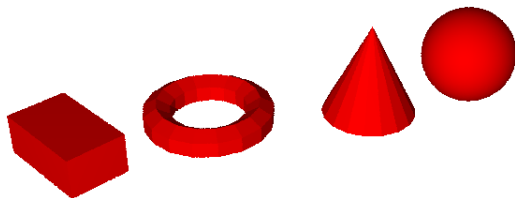
- based on `IndexFaceSet`
- easy to implement
  - override `get_grid()`
  - override `eval()` or `eval_c`
  - or pass into `__init__`
- automatically handles triangulation, bounding box, `is_enclosed`, etc.



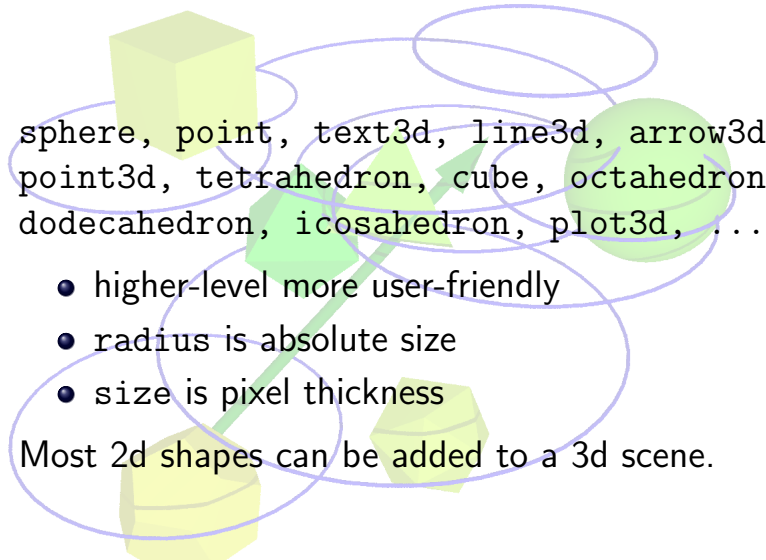
# Other Primitives

Sphere, Cone, Cylinder, Torus, LineSegment, Box

- based on ParametricSurface
- for efficiency, override more methods



# Still more shapes



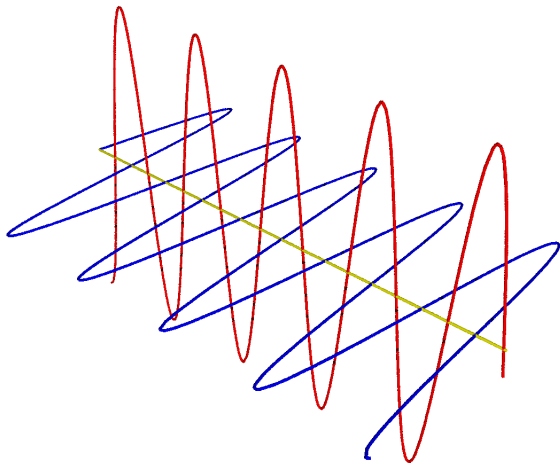
sphere, point, text3d, line3d, arrow3d,  
point3d, tetrahedron, cube, octahedron,  
dodecahedron, icosahedron, plot3d, ...

- higher-level more user-friendly
- radius is absolute size
- size is pixel thickness

Most 2d shapes can be added to a 3d scene.

# Still more shapes

```
sage: g = plot(10*sin(x), (x, 0, 30)).plot3d()
sage: g += plot(10*cos(x), (x, 0, 30), color='red').plot3d().rotate([1,0,0], pi/2)
sage: g += line3d([(0,0,0), (30,0,0)], color='yellow')
```





# Scenes

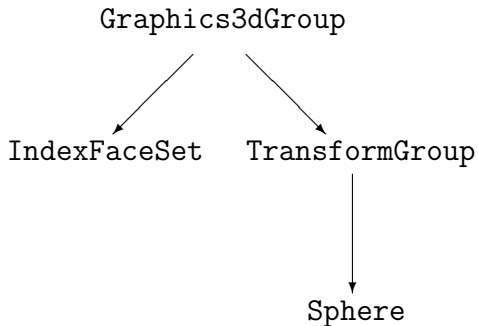
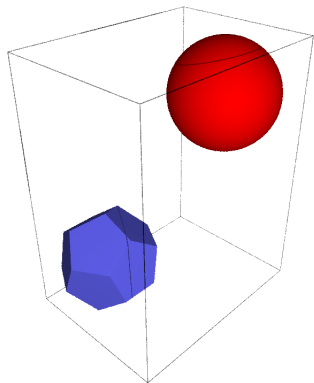
Objects in a 3D scene are laid out in a tree-like structure. There are three kinds of nodes:

- `Graphics3DGroup`
- `TransformGroup` — an affine transform of everything under it
- `PrimitiveObject` — an actual shape, as exemplified above

`TransformGroups` are created implicitly on `scale()`, `translate()`, or `rotate()`.

# A simple scene

```
sage: dodecahedron() + sphere((1,2,3), color='red')
```



# Rendering

Output to several formats:

- x3d
- jmol
- obj
- Tachyon

# Rendering

- rendering is done as a depth-first traversal of the tree
- a single object, `RenderParams` is passed which holds rendering state
- override `x3d_str()` or `x3d_geometry()`, call `x3d()`
- may produce several files

# Rendering

Color information is stored in a Texture object

- every object has an associated texture
- texture holds color, opacity, reflective effects, etc.
- texture knows how to render itself

# Putting it all together

Currently, the default viewer is Jmol

- all data (including driving script) is packed into a single .zip archive
- applet and app have constant rendering
- applet very customizable with javascript

Pure Java — may not be as fast as hardware accelerated graphics, but it's fast enough and works.

# Todo list

There is still *lots* to do

- better X3D support
- textures and bitmaps
- functions of complex variables
- viewpoints and lighting
- interactive feedback
- bugs
- ...